

RANGER MINI 2.0

CHIRONIX 

AGILEX

- » Four Wheel Independent Steering
- » Multiple Moving Modes
- » Hot Swap Modular Battery System
- » Four Wheel Independent Suspension
- » IP54 Dust-proof and Waterproof
- » Secondary Development Supported



MOTION CONTROL OF 4WD OMNIDIRECTIONAL ROBOT

The RANGER mini 2.0 is an upgraded version of the original RANGER mini. It provides an innovative design for a mobile robot that would operate within the context of an industrial application. It has flexible steering, strong manoeuvrability, a 0 turning radius, and can achieve 360° steering in situ by using 4*100W harmonic drives and 4*350W drive motor control systems.

INDEPENDENT SUSPENSIONS OFFER MORE FLEXIBILITY

RANGER mini 2.0 adopts a four-wheel independent suspension system with a load capacity of 80 kg, which can effectively improve the robot's manoeuvrability, pass-ability, and safety. It has the ability to adapt to difficult fields of various industry scenes, with an over 15° slope and 80 m over ridge.

MODULE DEVELOPMENT, FAST CHARGING AND BATTERY SWAPPING

RANGER mini 2.0 has a small size, high compatibility, long battery life, and is simple to maintain. It is outfitted with a variety of software and hardware interfaces and supports a wide range of top component applications.

It also supports fast charging and hot swapping functions to ensure that the robot always has power.

SPECIFICATIONS

DIMENSIONS (MM) (LXWXH)	738 x 500 x 338	OPERATING TIME	8hrs	GROUND CLEARANCE	107mm
WEIGHT	63 kg	MAX TRAVEL	30km	MOTOR	4 x 100 W steering and 4 x 350 W driving
MAX. PAYLOAD	80 kg	TURNING RADIUS	0mm	OPERATING TEMPERATURE	-10-40°C
MAX. SPEED	6km/h	BATTERY	48V 24Ah	COMMUNICATION	Standard CAN
MAX. INCLINE	15° (with load)	CHARGER	54.75V 20A	DRIVE TYPE	In-wheel Motor
STEERING	Four wheel Independent	CHARGING TIME	1.5hrs	PROTECTION LEVEL	IP54