Standard Bots RO1

Specs



Performance	Power consumption	Depends on program and payload; range from 25W to 1500W
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Collaboration operation Speed & force limiting per ISO/TS 15066, collision detection, and other safety functions

Ambient temperature range 0-55°C

Humidity 90%RH (non-condensing)

Operation Collaborative or high-speed non-collaborative

Specification Payload capacity 18kg (39 lbs)

Reach 1.3m (51.2 in)

Max joint speed 435° /s

Degrees of freedom 6

Physical Footprint Ø 200 mm

Materials Aluminum, steel, plastic

Cable length, robot arm2m (79 in)Weight, including cable32.5 kg (71.6 lbs)

IP classification IP54

Noise Depends on program; typically less than 58dB

Robot mounting Floor mount ¹

Tooltip connector Tool connector typeM8 8-pin & M8 4-pin

Compatibility Electrical and mechanical compatibility with largest gripper ecosystems

Native gripper support Two-finger, three-finger, and suction grippers

Tool I/O ports² Digital In: 2

Digital Out: 2 (Open-drain or push-pull, 1A)

Analog In: 2 (24V tolerant)

Analog Out: 0

RS-485 / UART max data rate: 10mbps

Tool power supply² 12V/24V, 3A continuous max

Control box IP classification IP54

IP class cleanroom N/A Ambient temperature range $0-55^{\circ}$ C

I/O ports Digital In: 16 (24V Tolerant)

Digital Out: 16 (24V 0.7A Out continuous)

24V 0.7A (3A combined if using internal power)

24V 0.7A (12A combined with external power supply)

Analog In: 4 (24V Tolerant)

Communication³ 24V I/O

TCP/IP Modbus TCP

Coming later this year via software update

RS-485 (UART / Modbus), USB 2.0, USB 3.0, CAN-FD

Power source 90 ~ 264VAC, 47-63Hz Humidity 90%RH (non-condensing)

Control box size (WxHxD) 460 mm x 430 mm x 315 mm (18.1 in x 16.9 in x 12.4 in)

Weight 14.4kg (31.7 lbs)

Materials Powder coated steel

Movement Repeatability +/- 0.025 mm

Shoulder 1 & 2 Working range: ±360°

Maximum speed: ±287°/sec

Elbow Working range: ±360°

Wrist 1, 2 & 3

Working range: ±360°

Maximum speed: ±435°/sec

Ceiling/wall mount enabled in software update.

^{2.} Hardware supported. Software support coming later this year via software update.

^{3.} More industrial protocols to be enabled via software update.